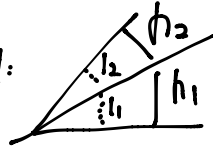


Lecture 3
Recall: (Last time)

Tool:  $\frac{h_1}{h_2} = \alpha = \frac{l_1}{l_2} = \dots$ similarity of Δs

intuitively

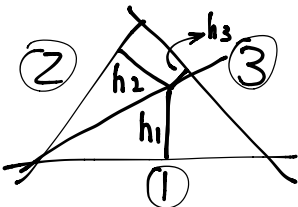


$$\frac{h_A}{h_B} = \frac{l_A}{l_B} = \alpha$$

两点共线
的结论

There are infinitely many lines passing O

$\Downarrow \times 3$



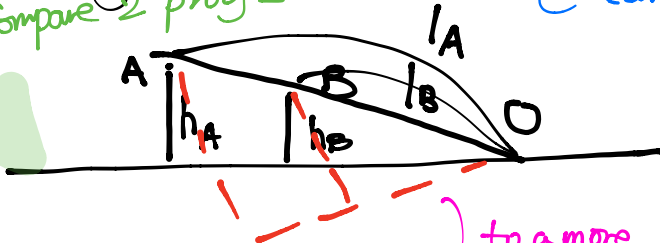
$$\frac{h_1}{h_2} = \alpha_1, \frac{h_2}{h_3} = \alpha_2, \frac{h_3}{h_1} = \alpha_3$$

三点共线的
充要条件

Whether h_1, h_2, h_3 pass 1 point? iff $\alpha_1 \alpha_2 \alpha_3 = 1$

Similarly
Compare 2 proofs

C can be on any line passing pt O.

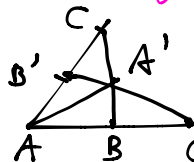


$$\frac{h_A}{h_B} = \alpha_1, \frac{h_B}{h_C} = \alpha_2, \frac{h_C}{h_A} = \alpha_3$$

they coincide $\Leftrightarrow \alpha_1 \alpha_2 \alpha_3 = 1$

to a more
complicated case 3 pts

Note: $\frac{C'A}{C'B} = \alpha_1$



$$\frac{C'A}{C'B} = \alpha_1, \frac{B'C}{B'A} = \alpha_2, \frac{A'B}{A'C} = \alpha_3$$

$$\alpha_1 \alpha_2 \alpha_3 = 1 \Leftrightarrow B', A', C' \text{ on one line}$$

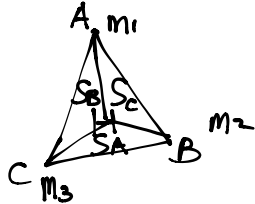
The necessary/sufficient condition for two points on the same line:
ratio of distances from two opposite vertices to the line = segment ratio on the line

BY SIMILAR TRIANGLE

So if we want to prove 3 pts on the same line then we should have 3 those conditions.

Assume we have a Δ & H , How to find COM exactly on H .

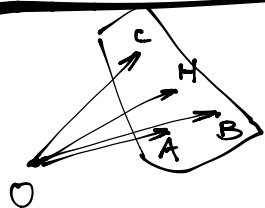
$$m_1 + m_2 + m_3 = 1$$



Recall using area to prove Ceva.

$$S_A + S_B + S_C = S$$

$$\text{Claim } m_B = \frac{S_B}{S}, m_C = \frac{S_C}{S}, m_A = \frac{S_A}{S}$$



$$\vec{H} = m_1 \vec{A} + m_2 \vec{B} + m_3 \vec{C}$$

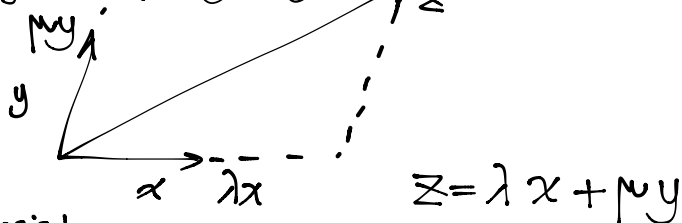
$$m_1 + m_2 + m_3 = 1$$

e.g. solve for m_1 , use Cramer's rule.

$$m_1 = \frac{\det(H, B, C)}{\det(A, B, C)}$$

actually this is equivalent to Cramer's rule

~~Algebra & Affine geometry~~



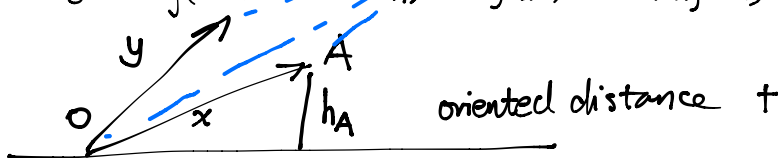
basis

x, y can be any non zero vector, we just need to change coordinates λ, μ .

$$\text{linear function: } f(\lambda a + \mu b) = \lambda f(a) + \mu f(b)$$

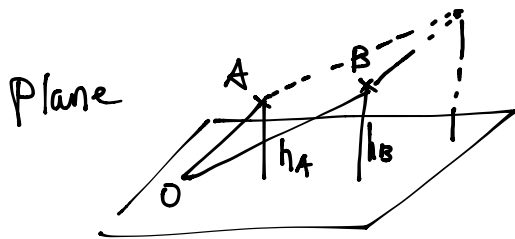
$$\text{so } f(z) = f(\lambda x + \mu y) = \lambda f(x) + \mu f(y)$$

$$\text{and } f(z) = f(\lambda_1 x_1 + \dots + \lambda_n x_n) = \lambda_1 f(x_1) + \dots + \lambda_n f(x_n)$$

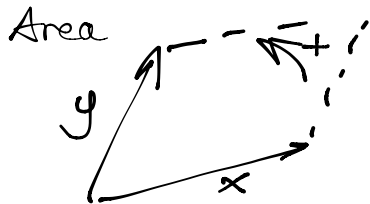


$$\text{Claim } h(x+y) = h(x) + h(y) \rightarrow \text{linear function}$$

Distance is a linear function if it is oriented.



+ half plane so oriented.
 So $S(x,y) = -S(y,x)$
 Still holds as a linear function



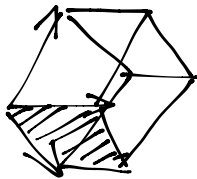
Consider oriented area (with + direction positive)

$S(x,y)$
 is also linear

$$S(x, \lambda y_1 + \mu y_2) = \lambda S(x, y_1) + \mu S(x, y_2)$$

$$S(x,y) = \text{length } x \cdot \text{height of } y$$

Volume
 $\text{Vol}(x,y,z)$



$$\text{Vol}(x,y,z) = \text{length } x \cdot \text{height of } y \cdot \text{height of } z.$$

$$x = \begin{pmatrix} a_{11} \\ a_{21} \end{pmatrix} \quad y = \begin{pmatrix} a_{12} \\ a_{22} \end{pmatrix} \quad \det(x,y) = \begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{pmatrix} = a_{11}a_{22} - a_{21}a_{12}$$

$$x = a_{11}e_1 + a_{21}e_2$$

$$\begin{aligned} S(x,y) &= S(x, a_{12}e_1 + a_{22}e_2) = a_{12}S(x, e_1) + a_{22}S(x, e_2) \\ &= a_{12}a_{21}S(e_1, e_1) + a_{22}a_{11}S(e_2, e_1) \\ &= -a_{12}a_{21} + a_{22}a_{11} \end{aligned}$$

proved

$$\begin{aligned} S(e_1, e_1) &= 0 & S(e_1, e_2) &= 1 \\ S(e_2, e_1) &= -1 & S(e_2, e_2) &= 0 \end{aligned}$$

Proof of

Cramer's Rule:

given x, y, z , find λ, μ s.t. $\lambda x + \mu y = z$

original: $\det(x,y)$

$$\text{consider } \det(z,y) = \det(\lambda x + \mu y, y) = \lambda \det(x,y) + \underbrace{\mu \det(y,y)}_0$$

$$\text{So } \frac{\det(z,y)}{\det(x,y)} = \lambda$$

$$\text{consider } \det(x,z) = \mu \det(x,y)$$

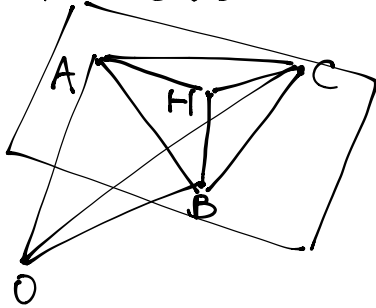
$$\text{so } \frac{\det(x,z)}{\det(x,y)} = \mu$$

For 3dim space, x, y, z , $w = \lambda x + \mu y + \gamma z$

$$\frac{\det(w,y,z)}{\det(x,y,z)} = \lambda \quad \text{due to the same reason} \dots$$

and $\frac{\det(x, w, z)}{\det(x, y, z)} = \mu$, $\frac{\det(x, y, w)}{\det(x, y, z)} = \gamma$

Back to Ceva :



$$\lambda + \mu + \gamma = 1$$

$$\lambda A + \mu B + \gamma C = H$$

$$(1, 0, 0) = A$$

$$(0, 1, 0) = B$$

$$(0, 0, 1) = C$$

$$\begin{aligned} \lambda &= \frac{\det(H, B, C)}{\det(A, B, C)} \\ &= \frac{S(H, B, C)}{S(A, B, C)} \end{aligned}$$