

## Midterm Exam II

November 18, 2011

No books. No notes. No calculators. No electronic devices of any kind.

Name \_\_\_\_\_

Student Number \_\_\_\_\_

**Problem 1.** (3 points)

Find the determinant of the matrix

$$\begin{pmatrix} 0 & 0 & x & 0 & 0 \\ 2 & 3 & 7 & 0 & 2 \\ 9 & 1 & 0 & 0 & 2 \\ x & 0 & 0 & 0 & 0 \\ 0 & 1 & x & 5 & 0 \end{pmatrix}$$

$$\begin{array}{l} \begin{vmatrix} \cancel{0} & \cancel{0} & \cancel{x} & \cancel{0} & \cancel{0} \\ 2 & 3 & 7 & 0 & 2 \\ 9 & 1 & 0 & 0 & 2 \\ x & 0 & 0 & 0 & 0 \\ 0 & 1 & x & 5 & 0 \end{vmatrix} \leftarrow \text{expand Row I} \\ \qquad \qquad \qquad \downarrow \text{expand Col III} \\ = x \begin{vmatrix} 2 & 3 & 0 & 2 \\ 9 & 1 & 0 & 2 \\ x & 0 & 0 & 0 \\ \cancel{0} & \cancel{1} & \cancel{x} & \cancel{5} & \cancel{0} \end{vmatrix} = -5x \begin{vmatrix} 2 & 3 & 2 \\ 9 & 1 & 2 \\ \cancel{x} & \cancel{0} & \cancel{0} \end{vmatrix} \leftarrow \text{expand Row III} \end{array}$$

$$= -5x^2 \begin{vmatrix} 3 & 2 \\ 1 & 2 \end{vmatrix} = -5x^2(6-2) = \underline{\underline{-20x^2}}$$

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**Problem 4.** (3 points)

Find the inverse of the matrix

$$\begin{pmatrix} 0 & 1 & 1 \\ 1 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix}$$

$$\left( \begin{array}{ccc|ccc} 0 & 1 & 1 & 1 & 0 & 0 \\ 1 & 0 & 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 & 0 & 1 \end{array} \right) \begin{array}{l} \uparrow \\ \downarrow \end{array} \rightarrow \left( \begin{array}{ccc|ccc} 1 & 0 & 1 & 0 & 1 & 0 \\ 0 & 1 & 1 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & 1 \end{array} \right) \begin{array}{l} -\text{II} \\ \\ \end{array}$$

$$\begin{array}{l} \uparrow \\ \uparrow \end{array} \left( \begin{array}{ccc|ccc} 1 & 0 & 1 & 0 & 1 & 0 \\ 0 & 1 & 1 & 1 & 0 & 0 \\ 0 & 0 & -1 & -1 & 0 & 1 \end{array} \right) \cdot (-1) \rightarrow \left( \begin{array}{ccc|ccc} 1 & 0 & 1 & 0 & 1 & 0 \\ 0 & 1 & 1 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 & 0 & -1 \end{array} \right) \begin{array}{l} -\text{III} \\ -\text{III} \\ \end{array}$$

$$\uparrow \left( \begin{array}{ccc|ccc} 1 & 0 & 0 & -1 & 1 & 1 \\ 0 & 1 & 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 1 & 0 & -1 \end{array} \right)$$

$$\begin{pmatrix} 0 & 1 & 1 \\ 1 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix}^{-1} = \begin{pmatrix} -1 & 1 & 1 \\ 0 & 0 & 1 \\ 1 & 0 & -1 \end{pmatrix}$$

1	2	3	4	5	6	total/25

3

**Problem 7.** (4 points)The matrix of a linear transformation  $T$  is

$$\begin{pmatrix} 0 & 2 & 1 & 1 & 1 \\ 0 & 2 & 1 & 0 & 1 \\ 0 & 4 & 2 & 1 & 2 \end{pmatrix}$$

- (a) Find a basis for the range of  $T$ .
- (b) The dimension of the domain of  $T$  is  $\# \text{ columns}(A) = 5$ .
- (c) The dimension of the null space of  $T$  is  $\# \text{ free vars} = 3$ .

$$\begin{pmatrix} 0 & 2 & 1 & 1 & 1 \\ 0 & 2 & 1 & 0 & 1 \\ 0 & 4 & 2 & 1 & 2 \end{pmatrix} \xrightarrow[-2I]{-I} \begin{pmatrix} 0 & 2 & 1 & 1 & 1 \\ 0 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 & 0 \end{pmatrix} \xrightarrow{-II} \begin{pmatrix} 0 & 2 & 1 & 1 & 1 \\ 0 & 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix}$$

row echelon form.

pivot columns = II and IV, so a basis for the range of  $T$  is  $\begin{pmatrix} 2 \\ 2 \\ 4 \end{pmatrix}, \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix}$ .

(remember:  $\text{range}(T) = \text{Column space of } [T]$ .)

**Problem 4.** (4 points)

Suppose  $T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$  is a linear transformation.

The scalar  $\lambda$  is called an *eigenvalue* of  $T$ , and the non-zero vector  $\vec{v}$  is called an *eigenvector* of  $T$ , corresponding to the eigenvalue  $\lambda$ , if

$$T(\vec{v}) = \lambda \vec{v}.$$

Suppose that  $T$  has eigenvalues  $\lambda_1 = 3$  and  $\lambda_2 = -1$ , and that  $\vec{v}_1 = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$  is an eigenvector of  $T$  corresponding to the eigenvalue 3 and  $\vec{v}_2 = \begin{pmatrix} 2 \\ -1 \end{pmatrix}$  is an eigenvector of  $T$  corresponding to the eigenvalue  $-1$ .

- (a) Find the matrix of  $T$  with respect to the basis  $\mathcal{B} = (\vec{v}_1, \vec{v}_2)$ .  
 (b) Find the standard matrix of  $T$ .

$$(a) \quad \left. \begin{aligned} T(\vec{v}_1) &= 3\vec{v}_1 = 3\vec{v}_1 + 0\vec{v}_2 \\ T(\vec{v}_2) &= -\vec{v}_2 = 0\vec{v}_1 - 1\vec{v}_2 \end{aligned} \right\} \text{so } [T]_{\mathcal{B}} = \begin{pmatrix} 3 & 0 \\ 0 & -1 \end{pmatrix}.$$

(b) the change of basis matrix is  $P = \begin{pmatrix} 1 & 2 \\ 1 & -1 \end{pmatrix}$ .

$$\begin{aligned} [T] &= P [T]_{\mathcal{B}} P^{-1} = \begin{pmatrix} -1 & 2 \\ 1 & -1 \end{pmatrix} \begin{pmatrix} 3 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} -1 & 2 \\ 1 & -1 \end{pmatrix}^{-1} \\ &= \begin{pmatrix} -3 & -2 \\ 3 & 1 \end{pmatrix} \begin{pmatrix} 1 & 2 \\ 1 & 1 \end{pmatrix} = \begin{pmatrix} -5 & -8 \\ 4 & 7 \end{pmatrix} \end{aligned}$$

**Problem 5.** (5 points)

Find the steady state vector of the Markov process with transition matrix  $A$  and initial state  $\vec{x}_0$ .

$$A = \begin{pmatrix} 0 & \frac{1}{2} & \frac{1}{3} \\ \frac{1}{2} & \frac{1}{4} & 0 \\ \frac{1}{2} & \frac{1}{4} & \frac{2}{3} \end{pmatrix} \quad \vec{x}_0 = \begin{pmatrix} 2 \\ 4 \\ 5 \end{pmatrix}$$

Space of fixed points is  $\text{Nul}(A - I)$ :

$$A - I = \begin{pmatrix} -1 & \frac{1}{2} & \frac{1}{3} \\ \frac{1}{2} & -\frac{3}{4} & 0 \\ \frac{1}{2} & \frac{1}{4} & -\frac{1}{3} \end{pmatrix} \begin{matrix} \cdot (-1) \\ \cdot 2 \\ \cdot 2 \end{matrix} \rightarrow \begin{pmatrix} 1 & -\frac{1}{2} & -\frac{1}{3} \\ 1 & -\frac{3}{2} & 0 \\ 1 & \frac{1}{2} & -\frac{2}{3} \end{pmatrix} \begin{matrix} -I \\ -I \\ -I \end{matrix}$$

$$\rightarrow \begin{pmatrix} 1 & -\frac{1}{2} & -\frac{1}{3} \\ 0 & -1 & \frac{1}{3} \\ 0 & 1 & -\frac{1}{3} \end{pmatrix} \begin{matrix} \\ +II \\ +II \end{matrix} \rightarrow \begin{pmatrix} 1 & -\frac{1}{2} & -\frac{1}{3} \\ 0 & -1 & \frac{1}{3} \\ 0 & 0 & 0 \end{pmatrix} \begin{matrix} \\ \cdot (-1) \\ \end{matrix} \rightarrow \begin{pmatrix} 1 & -\frac{1}{2} & -\frac{1}{3} \\ 0 & 1 & -\frac{1}{3} \\ 0 & 0 & 0 \end{pmatrix} \begin{matrix} +\frac{1}{2}II \\ \\ \end{matrix}$$

$$\rightarrow \begin{pmatrix} 1 & 0 & -\frac{1}{2} \\ 0 & 1 & -\frac{1}{3} \\ 0 & 0 & 0 \end{pmatrix} \text{ gen'l solution } \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} \frac{1}{2}z \\ \frac{1}{3}z \\ z \end{pmatrix} = z \begin{pmatrix} \frac{1}{2} \\ \frac{1}{3} \\ 1 \end{pmatrix}$$

total amount  $x + y + z = \text{const.} = 2 + 4 + 5 = 11$ .

need  $z$  s.t.  $\frac{1}{2}z + \frac{1}{3}z + z = 11$

$$\frac{3}{6}z + \frac{2}{6}z + \frac{6}{6}z = 11$$

$$\frac{11}{6}z = 11$$

$$\underline{\underline{z = 6}}$$

steady state vector is  $\underline{\underline{\begin{pmatrix} 3 \\ 2 \\ 6 \end{pmatrix}}}$

$$\text{so } \begin{pmatrix} x \\ y \\ z \end{pmatrix} = 6 \begin{pmatrix} \frac{1}{2} \\ \frac{1}{3} \\ 1 \end{pmatrix} = \begin{pmatrix} 3 \\ 2 \\ 6 \end{pmatrix}$$

**Problem 6.** (6 points)

The following dynamical system is given.

$$\begin{aligned} x_{n+1} &= & y_n & & x_0 &= 3 \\ y_{n+1} &= 2x_n + & y_n & & y_0 &= 0 \end{aligned}$$

- (a) Find explicit formulas for  $x_n$ , and  $y_n$ .  
 (b) Find the limiting growth rate of  $x_n$ , i.e., find  $\lim_{n \rightarrow \infty} \frac{x_{n+1}}{x_n}$ .  
 (c) Find the limiting proportion of  $x_n$  to  $y_n$ , i.e., find  $\lim_{n \rightarrow \infty} \frac{x_n}{y_n}$ .  
 (d) Can you find a non-trivial initial condition that will assure that the state vector stays bounded, i.e., does not grow beyond all bounds?

$$\begin{pmatrix} x_{n+1} \\ y_{n+1} \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ 2 & 1 \end{pmatrix} \begin{pmatrix} x_n \\ y_n \end{pmatrix}. \quad \text{transition matrix} = A = \begin{pmatrix} 0 & 1 \\ 2 & 1 \end{pmatrix}$$

$$\text{charpol.} = \det(A - \lambda I) = \begin{vmatrix} -\lambda & 1 \\ 2 & 1-\lambda \end{vmatrix} = \lambda(\lambda-1) - 2 = \lambda^2 - \lambda - 2 = (\lambda+1)(\lambda-2)$$

eigenvalues are  $\lambda=2$  and  $\lambda=-1$ .

$$\text{eigenvector for } \lambda=2: \begin{pmatrix} -2 & 1 \\ 2 & -1 \end{pmatrix} \rightarrow \begin{pmatrix} 2 & -1 \\ 0 & 0 \end{pmatrix} \quad \vec{v} = \begin{pmatrix} 1 \\ 2 \end{pmatrix}$$

$$\text{eigenvector for } \lambda=-1: \begin{pmatrix} 1 & 1 \\ 2 & 2 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 1 \\ 0 & 0 \end{pmatrix} \quad \vec{v} = \begin{pmatrix} 1 \\ -1 \end{pmatrix}.$$

$$\text{general solution: } \begin{pmatrix} x_n \\ y_n \end{pmatrix} = c_1 2^n \begin{pmatrix} 1 \\ 2 \end{pmatrix} + c_2 (-1)^n \begin{pmatrix} 1 \\ -1 \end{pmatrix}.$$

$$\text{initial condition: } \begin{pmatrix} x_0 \\ y_0 \end{pmatrix} = c_1 \begin{pmatrix} 1 \\ 2 \end{pmatrix} + c_2 \begin{pmatrix} 1 \\ -1 \end{pmatrix} \quad \begin{pmatrix} 1 & 1 \\ 2 & -1 \end{pmatrix} \begin{pmatrix} c_1 \\ c_2 \end{pmatrix} = \begin{pmatrix} 3 \\ 0 \end{pmatrix}.$$

$$\left( \begin{array}{cc|c} 1 & 1 & 3 \\ 2 & -1 & 0 \end{array} \right) \rightarrow \left( \begin{array}{cc|c} 1 & 1 & 3 \\ 0 & -3 & -6 \end{array} \right) \rightarrow \left( \begin{array}{cc|c} 1 & 1 & 3 \\ 0 & 1 & 2 \end{array} \right) \rightarrow \left( \begin{array}{cc|c} 1 & 0 & 1 \\ 0 & 1 & 2 \end{array} \right) \quad \begin{pmatrix} c_1 \\ c_2 \end{pmatrix} = \begin{pmatrix} 1 \\ 2 \end{pmatrix}.$$

$$\begin{pmatrix} x_n \\ y_n \end{pmatrix} = 2^n \begin{pmatrix} 1 \\ 2 \end{pmatrix} + (-1)^n \begin{pmatrix} 2 \\ -2 \end{pmatrix}.$$

$$(a) \quad \boxed{\begin{aligned} x_n &= 2^n + 2(-1)^n \\ y_n &= 2 \cdot 2^n - 2(-1)^n \end{aligned}}$$

$$\begin{aligned}
 (b) \quad \lim_{n \rightarrow \infty} \frac{x_{n+1}}{x_n} &= \lim_{n \rightarrow \infty} \frac{2^{n+1} - 2(-1)^{n+1}}{2^n - 2(-1)^n} = \lim_{n \rightarrow \infty} \frac{2 \cdot 2^n + 2(-1)^n}{2^n - 2(-1)^n} \\
 &= \lim_{n \rightarrow \infty} 2 \frac{1 + 2(-\frac{1}{2})^n}{1 - 2(-\frac{1}{2})^n} = 2 \frac{1 + 0}{1 - 0} = 2.
 \end{aligned}$$

$$(c) \quad \lim_{n \rightarrow \infty} \frac{x_n}{y_n} = \frac{1}{2}$$

(d)  $c_1 = 0$   $c_2 = 1$  works. this would be

$$\begin{pmatrix} x_0 \\ y_0 \end{pmatrix} = 0 \begin{pmatrix} 1 \\ 2 \end{pmatrix} + 1 \begin{pmatrix} 1 \\ -1 \end{pmatrix} = \begin{pmatrix} 1 \\ -1 \end{pmatrix}.$$

$$\begin{pmatrix} 0 & 1 \\ 2 & 1 \end{pmatrix} \begin{pmatrix} 1 \\ -1 \end{pmatrix} = \begin{pmatrix} -1 \\ 1 \end{pmatrix}$$

$$\begin{pmatrix} 0 & 1 \\ 2 & 1 \end{pmatrix} \begin{pmatrix} -1 \\ 1 \end{pmatrix} = \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$

with initial condition  $\begin{pmatrix} x_0 \\ y_0 \end{pmatrix} = \begin{pmatrix} 1 \\ -1 \end{pmatrix}$  the system oscillates between the two states  $\begin{pmatrix} 1 \\ -1 \end{pmatrix}$  and  $\begin{pmatrix} -1 \\ 1 \end{pmatrix}$ .

So the state vectors stay bounded.

(only the eigenvalue  $\lambda = -1$  is used because the state vectors  $\begin{pmatrix} 1 \\ -1 \end{pmatrix}$  and  $\begin{pmatrix} -1 \\ 1 \end{pmatrix}$  are in the eigenspace  $E_{-1}$ , so they stay in  $E_{-1}$ .)