

Department of Mathematics, University of Toronto  
**MAT224H1F - Linear Algebra II**  
Fall 2013

**Problem Set 1 Solutions**

1. (a) Find the number  $x \in \{0, 1, 2, 3, 4, 5, 6\}$  such that  $x = 3^{-1}$  in  $\mathbb{Z}_7$ .  
(b) Express the complex number  $\frac{(2i+1)(i^3+i+1)}{1-i}$  in the form  $a + bi$ , with  $a, b \in \mathbb{R}$ .

**Solution.**

- (a) By definition of multiplicative inverses, the  $x$  we are looking for satisfies  $3x = 1$  in  $\mathbb{Z}_7$ . We know from class that  $\mathbb{Z}_7$  is a field, so exactly one such  $x$  exists. The easiest way to find it is to start multiplying 3 by each element of  $\{0, 1, 2, 3, 4, 5, 6\}$  until we find one that works. All the computations are done mod 7:

$$\begin{aligned}3 * 0 &= 0 \neq 1 \\3 * 1 &= 3 \neq 1 \\3 * 2 &= 6 \neq 1 \\3 * 3 &= 9 = 2 \neq 1 \\3 * 4 &= 12 = 5 \neq 1 \\3 * 5 &= 15 = 1\end{aligned}$$

So  $5 = 3^{-1}$  in  $\mathbb{Z}_7$ .

- (b) Start by simplifying the numerator. Note that  $i^3 = i^2 \cdot i = (-1) \cdot i = -i$ .

$$(2i + 1)(i^3 + i + 1) = (2i + 1)(-i + i + 1) = 2i + 1.$$

The easiest way to simplify a fraction in  $\mathbb{C}$  is to multiply the numerator and denominator by the conjugate of the denominator, then simplify, remembering that  $i^2 = -1$ .

$$\begin{aligned}\frac{(2i + 1)(i^3 + i + 1)}{1 - i} &= \frac{2i + 1}{1 - i} \\&= \frac{2i + 1}{1 - i} \left( \frac{1 + i}{1 + i} \right) \\&= \frac{2i + 1 + 2i^2 + i}{1 - i + i - i^2} \\&= \frac{-1 + 3i}{2} \\&= \frac{-1}{2} + \frac{3}{2}i\end{aligned}$$

2. Recall that if  $p$  is a prime, then for any  $n$ ,  $\mathbb{Z}_p^n = \{(x_1, \dots, x_n) : x_1, \dots, x_n \in \mathbb{Z}_p\}$  is a vector space over  $\mathbb{Z}_p$  with pointwise addition and scalar multiplication mod  $p$ .
- (a) Consider the subspace  $S = \text{span}\{(1, 1, 1), (2, 3, 4)\}$  of  $\mathbb{Z}_5^3$ . Does the vector  $(0, 1, 0)$  belong to  $S$ ? Does the vector  $(3, 1, 4)$  belong to  $S$ ?
- (b) Find a basis for the subspace  $S = \text{span}\{(2, 1, 0, 2), (1, 0, 1, 4), (0, 1, 3, 4)\}$  of  $\mathbb{Z}_5^4$ .

**Solution.**

- (a) The vector  $(0, 1, 0)$  is in  $S$  if and only if we can find  $a, b \in \mathbb{Z}_5$  such that  $a(1, 1, 1) + b(2, 3, 4) = (0, 1, 0)$ , with the computations done mod 5. This equation is an abbreviated way of writing a system of three equations in the unknowns  $a, b$ :

$$\begin{aligned} a + 2b &= 0 \\ a + 3b &= 1 \\ a + 4b &= 0 \end{aligned}$$

Any of the usual methods for solving such a system will work, as long as we remember to make the computations mod 5. We use an augmented matrix and row-reduce:

$$\left[ \begin{array}{cc|c} 1 & 2 & 0 \\ 1 & 3 & 1 \\ 1 & 4 & 0 \end{array} \right] \rightarrow \left[ \begin{array}{cc|c} 1 & 2 & 0 \\ 0 & 1 & 1 \\ 0 & 2 & 0 \end{array} \right].$$

From this partially row-reduced form we see that we must have  $2b = 0$  and  $b = 1$ . There is no  $b \in \mathbb{Z}_5$  satisfying both of these equations, so  $(0, 1, 0) \notin S$ .

For the vector  $(3, 1, 4)$ , we repeat the above process of forming an augmented matrix and row-reducing:

$$\begin{aligned} \left[ \begin{array}{cc|c} 1 & 2 & 3 \\ 1 & 3 & 1 \\ 1 & 4 & 4 \end{array} \right] &\rightarrow \left[ \begin{array}{cc|c} 1 & 2 & 3 \\ 0 & 1 & -2 \\ 0 & 2 & 1 \end{array} \right] \\ &\rightarrow \left[ \begin{array}{cc|c} 1 & 0 & 2 \\ 0 & 1 & -2 \\ 0 & 1 & 2^{-1} \end{array} \right] \end{aligned}$$

From this row-reduced matrix we see that there is a solution if and only if  $-2 = 2^{-1}$  in  $\mathbb{Z}_5$ . Calculating mod 5, we have  $-2 = 3$ , and  $3 \cdot 2 = 6 = 1$ , so  $3 = 2^{-1}$ . Thus  $(2, 3)$  is a solution to our system of equations, and  $(3, 1, 4) = 2(1, 1, 1) + 3(2, 3, 4) \in S$ .

- (b) In MAT223 you saw how to solve a problem like this over the field  $\mathbb{R}$ , and the same technique works here - we just need to remember to calculate mod 5. We form a matrix whose columns are the vectors in the given spanning set, then we row-reduce. The columns of the original matrix

corresponding to the columns of the row-reduced matrix with leading 1's will form a basis for  $S$ .

$$\begin{aligned} \begin{bmatrix} 2 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 3 \\ 2 & 4 & 4 \end{bmatrix} &\rightarrow \begin{bmatrix} 0 & 1 & -2 \\ 1 & 0 & 1 \\ 0 & 1 & 3 \\ 0 & 4 & 2 \end{bmatrix} \\ &= \begin{bmatrix} 0 & 1 & 3 \\ 1 & 0 & 1 \\ 0 & 1 & 3 \\ 0 & 4 & 2 \end{bmatrix} \\ &\rightarrow \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 3 \\ 0 & 2 & 1 \\ 0 & 0 & 0 \end{bmatrix} \\ &\rightarrow \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 3 \\ 0 & 0 & -5 \\ 0 & 0 & 0 \end{bmatrix} \\ &= \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 3 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \end{aligned}$$

We see that the first two columns have leading 1's, so a basis for  $S$  is  $\{(2, 1, 0, 2), (1, 0, 1, 4)\}$ .

3. (a) Consider the subspace  $S = \text{span} \{ (1, 2, 3, 4), (4, 5, 6, 2), (2, 5, 1, 1), (0, 4, 1, 0) \}$  of  $\mathbb{Z}_7^4$ . Find the dimension of  $S$ .
- (b) Consider the subspace  $S = \text{span} \{ (i, 0, 1), (1, i, -1), (i, i - 1, -1) \}$  of  $\mathbb{C}^3$ . Find the dimension of  $S$ .

**Solution.**

Recall from MAT223 that to solve questions of this kind over  $\mathbb{R}$ , we can put the given spanning vectors as the columns of a matrix and row-reduce. The number of columns with leading 1's will be the dimension of the subspace  $S$ . The same technique works here, except that now we do our calculations in other fields ( $\mathbb{Z}_7$  for part (a),  $\mathbb{C}$  for part (b)).

- (a) We follow the description above, remembering as we row-reduce that all calculations are done in  $\mathbb{Z}_7$ .

$$\begin{aligned}
 \begin{bmatrix} 1 & 4 & 2 & 0 \\ 2 & 5 & 5 & 4 \\ 3 & 6 & 1 & 1 \\ 4 & 2 & 1 & 0 \end{bmatrix} &\rightarrow \begin{bmatrix} 1 & 4 & 2 & 0 \\ 7 & 25 & 15 & 4 \\ 7 & 22 & 9 & 1 \\ 7 & 14 & 7 & 0 \end{bmatrix} \\
 &= \begin{bmatrix} 1 & 4 & 2 & 0 \\ 0 & 4 & 1 & 4 \\ 0 & 1 & 2 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix} \\
 &\rightarrow \begin{bmatrix} 1 & 4 & 2 & 0 \\ 0 & 4 & 1 & 4 \\ 0 & 4 & 8 & 4 \\ 0 & 0 & 0 & 0 \end{bmatrix} \\
 &= \begin{bmatrix} 1 & 4 & 2 & 0 \\ 0 & 4 & 1 & 4 \\ 0 & 4 & 1 & 4 \\ 0 & 0 & 0 & 0 \end{bmatrix} \\
 &\rightarrow \begin{bmatrix} 1 & 4 & 2 & 0 \\ 0 & 8 & 2 & 8 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \\
 &= \begin{bmatrix} 1 & 4 & 2 & 0 \\ 0 & 1 & 2 & 1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}
 \end{aligned}$$

We see that there are two leading 1's, so  $\dim(S) = 2$ .

- (b) We again follow the description from above, this time doing the row-reduction calculations in  $\mathbb{C}$ .

$$\begin{aligned}
 \begin{bmatrix} i & 1 & i \\ 0 & i & i - 1 \\ 1 & -1 & -1 \end{bmatrix} &\rightarrow \begin{bmatrix} -1 & i & -1 \\ 0 & 1 & 1 + i \\ 1 & -1 & -1 \end{bmatrix} \\
 &\rightarrow \begin{bmatrix} -1 & i & -1 \\ 0 & 1 & i + 1 \\ 0 & i - 1 & -2 \end{bmatrix} \\
 &\rightarrow \begin{bmatrix} 1 & -i & 1 \\ 0 & 1 & i + 1 \\ 0 & 0 & 0 \end{bmatrix}
 \end{aligned}$$

Here the last line was obtained by subtracting  $(i - 1)$  times the second row from the third row. We see that there are two leading 1's, so  $\dim(S) = 2$ .

4. Let  $T : P_2(\mathbb{C}) \rightarrow P_3(\mathbb{C})$  be defined by  $T(p(x)) = (x+i)(p(x+i))$ .

- (a) Show that  $T$  is linear.
- (b) Let  $\alpha = \{1, x, x^2\}$  and  $\beta = \{1, x, x^2, x^3\}$  be bases for  $P_2(\mathbb{C})$  and  $P_3(\mathbb{C})$ , respectively. Compute  $[T]_{\alpha}^{\beta}$ .
- (c) Find a basis for  $\text{im}(T)$  and find a basis for  $\text{ker}(T)$ .

**Solution.**

- (a) Let  $p(x) = a_2x^2 + a_1x + a_0$ , and  $q(x) = b_2x^2 + b_1x + b_0$ , and let  $r, s \in \mathbb{C}$ . As we saw in class, it suffices to check

$$T(rp(x) + sq(x)) = rT(p(x)) + sT(q(x)).$$

We compute:

$$\begin{aligned} T(rp(x) + sq(x)) &= T((ra_2 + sb_2)x^2 + (ra_1 + sb_1)x + (ra_0 + sb_0)) \\ &= (x+i)((ra_2 + sb_2)(x+i)^2 + (ra_1 + sb_1)(x+i) + (ra_0 + sb_0)) \\ &= (x+i)(ra_2(x+i)^2 + ra_1(x+i) + ra_0 + sb_2(x+i)^2 + sb_1(x+i) + sb_0) \\ &= r(x+i)(a_2(x+i)^2 + a_1(x+i) + a_0) + s(x+i)(b_2(x+i)^2 + b_1(x+i) + b_0) \\ &= rT(a_2x^2 + a_1x + a_0) + sT(b_2x^2 + b_1x + b_0) \\ &= rT(p(x)) + sT(q(x)) \end{aligned}$$

This proves that  $T$  is linear.

- (b) Recall that the function  $1 \in \alpha$  is the function  $1(x) = 1$  for all  $x \in \mathbb{C}$ . We thus have  $1(x+i) = 1$  as well. We compute:

$$\begin{aligned} T(1) &= (x+i)1 \\ &= x+i \\ &= i \cdot 1 + 1 \cdot x + 0 \cdot x^2 + 0 \cdot x^3 \\ T(x) &= (x+i)(x+i) \\ &= (x+i)^2 \\ &= x^2 + 2ix + i^2 \\ &= (-1) \cdot 1 + (2i) \cdot x + 1 \cdot x^2 + 0 \cdot x^3 \\ T(x^2) &= (x+i)(x+i)^2 \\ &= (x+i)^3 \\ &= x^3 + 2ix^2 - x + ix^2 + 2i^2x - i \\ &= (-i) \cdot 1 + (-3) \cdot x + (3i) \cdot x^2 + 1 \cdot x^3 \end{aligned}$$

We have expressed each  $T(v)$ , for  $v \in \alpha$ , in terms of the basis  $\beta$ . The coefficients then give us the columns of  $[T]_{\alpha}^{\beta}$ . Remember that the order matters, so the first entry of the first column will be the coefficient of 1 in  $T(1)$ . We thus have:

$$[T]_{\alpha}^{\beta} = \begin{bmatrix} i & -1 & -i \\ 1 & 2i & -3 \\ 0 & 1 & 3i \\ 0 & 0 & 1 \end{bmatrix}.$$

(c) Starting from  $[T]_{\alpha}^{\beta}$ , we row-reduce:

$$\begin{aligned} \begin{bmatrix} i & -1 & -i \\ 1 & 2i & -3 \\ 0 & 1 & 3i \\ 0 & 0 & 1 \end{bmatrix} &\rightarrow \begin{bmatrix} i & -1 & 0 \\ 1 & 2i & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \\ &\rightarrow \begin{bmatrix} i & 0 & 0 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \\ &\rightarrow \begin{bmatrix} 0 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \end{aligned}$$

From this we see that all three columns have leading 1's. This tells us that the columns of the original matrix form a basis for  $\text{im}([T]_{\alpha}^{\beta})$ . We know from class that the vectors in  $P_3(\mathbb{C})$  whose coordinates with respect to  $\beta$  are the columns of  $[T]_{\alpha}^{\beta}$  then form a basis for  $\text{im}(T)$ . That is, a basis for  $\text{im}(T)$  is:

$$\{x + i, x^2 + 2i - 1, x^3 + 3ix^2 - 3x - i\}.$$

We also see from the row-reduced matrix that the null space of  $[T]_{\alpha}^{\beta}$  is trivial. As we saw in class, this means that  $\ker(T) = \{0\}$  as well. This means that  $\ker(T)$  has dimension 0; a basis for  $\ker(T)$  is therefore  $\emptyset$ , the set with no elements.

5. Let  $T : \mathbb{R}^2 \rightarrow \mathbb{R}^3$  be the linear transformation whose matrix with respect to the bases  $\alpha = \{ (1, 1), (1, -1) \}$  of  $\mathbb{R}^2$  and  $\beta = \{ (1, 0, 1), (2, 2, 0), (0, -1, 1) \}$  of  $\mathbb{R}^3$  is:

$$[T]_{\alpha}^{\beta} = \begin{bmatrix} 1 & 1 \\ 0 & -1 \\ 4 & 2 \end{bmatrix}.$$

Find  $T(x, y)$  for all  $(x, y) \in \mathbb{R}^2$ .

**Solution.**

For any  $(x, y) \in \mathbb{R}^2$ , we can write  $[(x, y)]_{\alpha} = (a, b)$ , where  $(x, y) = a(1, 1) + b(1, -1)$ . To find  $a, b$  we solve the system of equations  $x = a + b$ ,  $y = a - b$  to find  $a = \frac{x+y}{2}$  and  $b = \frac{x-y}{2}$ . We then have

$$\begin{aligned} [T(x, y)]_{\beta} &= [T]_{\alpha}^{\beta} [(x, y)]_{\alpha} \\ &= \begin{bmatrix} 1 & 1 \\ 0 & -1 \\ 4 & 2 \end{bmatrix} \begin{bmatrix} \frac{x+y}{2} \\ \frac{x-y}{2} \end{bmatrix} \\ &= \left( \frac{x+y}{2} + \frac{x-y}{2}, -\frac{x-y}{2}, 4\frac{x+y}{2} + 2\frac{x-y}{2} \right) \\ &= \left( x, \frac{y-x}{2}, 3x+y \right) \end{aligned}$$

Thus for any  $(x, y) \in \mathbb{R}^2$ ,

$$\begin{aligned} T(x, y) &= x(1, 0, 1) + \frac{y-x}{2}(2, 2, 0) + (3x+y)(0, -1, 1) \\ &= (x, 0, x) + (y-x, y-x, 0) + (0, -3x-y, 3x+y) \\ &= (y, -4x-2y, 4x+y) \end{aligned}$$

6. Let  $T : \mathbb{R}^3 \rightarrow \mathbb{R}^3$  be defined by

$$T(x, y, z) = (2x - y - z, x + 3y + 2z, y)$$

Find  $[T]_{\alpha}^{\beta}$ , where  $\alpha = \{ (0, 1, 1), (1, 1, 0), (1, 0, 1) \}$  and  $\beta = \{ (2, -1, 1), (1, 1, 1), (0, 0, 1) \}$ .

**Solution.**

We first find the first column, which will be the sequence of numbers  $v$  such that  $[T(0, 1, 1)]_{\beta} = v$ . Straightforward computation gives

$$T(0, 1, 1) = (-2, 5, 1).$$

We need to write  $(-2, 5, 1) = a(2, -1, 1) + b(1, 1, 1) + c(0, 0, 1)$ . This gives a system of equations:

$$\begin{aligned} 2a + b &= -2 \\ -a + b &= 5 \\ a + b + c &= 1 \end{aligned}$$

Solving this system of equations, we obtain  $a = -\frac{7}{3}, b = \frac{8}{3}, c = \frac{2}{3}$ . The first column of  $[T]_{\alpha}^{\beta}$  will

therefore be  $\begin{bmatrix} -\frac{7}{3} \\ \frac{8}{3} \\ \frac{2}{3} \end{bmatrix}$ .

Next, we have  $T(1, 1, 0) = (1, 4, 1)$ , and solving  $(1, 4, 1) = a(2, -1, 1) + b(1, 1, 1) + c(0, 0, 1)$  gives  $a = -1, b = 3, c = -1$ .

Finally,  $T(1, 0, 1) = (1, 3, 0)$ , and solving  $(1, 3, 0) = a(2, -1, 1) + b(1, 1, 1) + c(0, 0, 1)$  gives  $a = -\frac{2}{3}, b = \frac{7}{3}, c = -\frac{5}{3}$ .

Therefore, the matrix  $[T]_{\alpha}^{\beta}$  is

$$[T]_{\alpha}^{\beta} = \begin{bmatrix} -\frac{7}{3} & -1 & -\frac{2}{3} \\ \frac{8}{3} & 3 & \frac{7}{3} \\ \frac{2}{3} & -1 & -\frac{5}{3} \end{bmatrix}.$$

7. (a) Prove that  $\mathbb{Z}_{10}$  (with the operations of addition and multiplication modulo 10) is not a field. *Hint:* Find a non-zero element of  $\mathbb{Z}_{10}$  which does not have a multiplicative inverse.
- (b) Prove that if  $n \in \mathbb{N}$  is not prime, then  $\mathbb{Z}_n$  is not a field. *Hint:* Write  $n = k \cdot m$ , where  $k, m > 1$  and  $k, m < n$ . The element  $k \in \mathbb{Z}_n$  is non-zero - show that it does not have a multiplicative inverse by considering the meaning of the equation  $k \cdot a = 1$  in  $\mathbb{Z}_n$ .

**Solution.**

- (a) We will show that  $2 \in \mathbb{Z}_{10}$  does not have a multiplicative inverse. We know that  $2 \neq 0$  in  $\mathbb{Z}_{10}$ , so this will suffice to show that  $\mathbb{Z}_{10}$  is not a field. The easiest way to prove there is no inverse for 2 is to simply compute  $2 \cdot x \pmod{10}$  for each  $x \in \{0, 1, \dots, 9\}$ , and see that we never get the value 1.

$$\begin{aligned}
 2 \cdot 0 &= 0 \neq 1 \\
 2 \cdot 1 &= 2 \neq 1 \\
 2 \cdot 2 &= 4 \neq 1 \\
 2 \cdot 3 &= 6 \neq 1 \\
 2 \cdot 4 &= 8 \neq 1 \\
 2 \cdot 5 &= 10 = 0 \neq 1 \\
 2 \cdot 6 &= 12 = 2 \neq 1 \\
 2 \cdot 7 &= 14 = 4 \neq 1 \\
 2 \cdot 8 &= 16 = 6 \neq 1 \\
 2 \cdot 9 &= 18 = 8 \neq 1
 \end{aligned}$$

An alternate solution would be to solve part (b) first, then observe that  $10 = 2 \cdot 5$  is not prime.

- (b) As suggested by the hint, use the fact that  $n$  is not prime to write  $n = k \cdot m$ , where  $k, m > 1$ . Notice that the conditions on  $k, m$  imply that  $0 < k < n$ , so  $k$  is not 0 in  $\mathbb{Z}_n$ . Suppose for a contradiction that  $k$  has a multiplicative inverse in  $\mathbb{Z}_n$ . Then there is some  $a \in \{0, 1, \dots, n-1\}$  such that  $a \cdot k = 1$  in  $\mathbb{Z}_n$ . By definition, this equation means that there is some  $l \in \mathbb{Z}$  such that  $a \cdot k = 1 + l \cdot n$ . Rearranging this equation, we get:

$$a \cdot k - l \cdot n = 1.$$

Again using that  $n = k \cdot m$ , we have:

$$a \cdot k - l \cdot k \cdot m = 1.$$

So

$$k(a - l \cdot m) = 1.$$

Here  $a, l, n \in \mathbb{Z}$ , so  $a - l \cdot m \in \mathbb{Z}$  as well. This equation says that there is some integer  $r$  such that  $k \cdot r = 1$ . We chose  $k > 1$ , so this is impossible. Therefore  $k$  is a non-zero element of  $\mathbb{Z}_n$  without a multiplicative inverse, so  $\mathbb{Z}_n$  is not a field.

8. Let  $T : M_{2 \times 2}(\mathbb{R}) \rightarrow M_{2 \times 2}(\mathbb{R})$  be defined by

$$T(A) = A - A^t.$$

(Recall that  $A^t$  is the transpose of  $A$ ). Find the dimension of  $\ker(T)$  and the dimension of  $\text{im}(T)$ . You may assume without proof that  $T$  is linear.

**Solution.**

Let  $\alpha = \left\{ \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \right\}$ . This  $\alpha$  is a basis for  $M_{2 \times 2}(\mathbb{R})$ , as you saw in MAT223. We compute:

$$\begin{aligned} T \left( \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} \right) &= \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix} \\ T \left( \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} \right) &= \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} = 1 \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} + (-1) \begin{bmatrix} 0 & 0 \\ -1 & 0 \end{bmatrix} \\ T \left( \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix} \right) &= \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix} = (-1) \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} + 1 \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix} \\ T \left( \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \right) &= \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix} \end{aligned}$$

Hence

$$[T]_{\alpha}^{\alpha} = \begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 1 & -1 & 0 \\ 0 & -1 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}.$$

This matrix row-reduces to

$$\begin{bmatrix} 0 & 1 & -1 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}.$$

There is one leading 1, so  $\dim \text{im}(T) = 1$ , and  $\dim \ker(T) = 3$ .

9. Let  $V$  be a vector space over a field  $F$ , and let  $W_1, W_2$  be subspaces of  $V$ . We say that  $V$  is the *direct sum* of  $W_1$  and  $W_2$ , and write  $V = W_1 \oplus W_2$ , if  $V = W_1 + W_2$  and  $W_1 \cap W_2 = \{0\}$ .

Prove that  $V = W_1 \oplus W_2$  if and only if for each  $v \in V$  there are unique  $w_1 \in W_1$  and  $w_2 \in W_2$  such that  $v = w_1 + w_2$ .

**Solution.**

Assume  $V = W_1 \oplus W_2$ , and consider any  $v \in V$ . Part of the definition of  $V = W_1 \oplus W_2$  is that  $V = W_1 + W_2$ , so  $v \in W_1 + W_2$ , i.e., there exist  $w_1 \in W_1$  and  $w_2 \in W_2$  such that  $v = w_1 + w_2$ . This shows existence, but we must still show uniqueness. Suppose that  $w'_1 \in W_1$  and  $w'_2 \in W_2$  are such that  $v = w_1 + w_2 = w'_1 + w'_2$ . We must show that  $w_1 = w'_1$  and  $w_2 = w'_2$ . We know that  $w_1 + w_2 = w'_1 + w'_2$ , which we can rearrange as  $w_1 - w'_1 = w'_2 - w_2$ . Now  $W_1$  is a subspace of  $V$ , and  $w_1, w'_1 \in W_1$ , so  $w_1 - w'_1 \in W_1$ . Similarly,  $w'_2 - w_2 \in W_2$ , which is the same as saying  $w_1 - w'_1 \in W_2$ . So  $w_1 - w'_1 \in W_1 \cap W_2$ . By definition of  $V = W_1 \oplus W_2$ , we have  $W_1 \cap W_2 = \{0\}$ , so  $w_1 - w'_1 = 0$ . That is,  $w_1 = w'_1$ . We already had  $w_1 - w'_1 = w'_2 - w_2$ , and we now know  $w_1 - w'_1 = 0$ , so  $w'_2 - w_2 = 0$ , and hence  $w'_2 = w_2$  as well. This proves uniqueness.

Now assume that for each  $v \in V$  there are unique  $w_1 \in W_1$  and  $w_2 \in W_2$  such that  $v = w_1 + w_2$ . Given any  $v \in V$  we thus have  $v \in W_1 + W_2$ , so  $V \subseteq W_1 + W_2$ . The reverse containment is always true, so we conclude  $V = W_1 + W_2$ . We still need to show that  $W_1 \cap W_2 = \{0\}$ . Suppose that  $v \in W_1 \cap W_2$ . Let  $w_1 = v$ , and  $w_2 = 0$ . Then  $w_1 \in W_1, w_2 \in W_2$ , and  $v = w_1 + w_2$ . Let  $w'_1 = 0$  and  $w'_2 = v$ . Then again,  $w'_1 \in W_1, w'_2 \in W_2$ , and  $v = w'_1 + w'_2$ . By hypothesis there is a *unique* way of writing  $v$  as a sum of a vector in  $W_1$  and a vector in  $W_2$ , so we must have  $w_1 = w'_1$  and  $w_2 = w'_2$ . That is,  $v = w_1 = w'_1 = 0$ , so  $v = 0$ . This proves that  $W_1 \cap W_2 = \{0\}$ , so  $V = W_1 \oplus W_2$ .